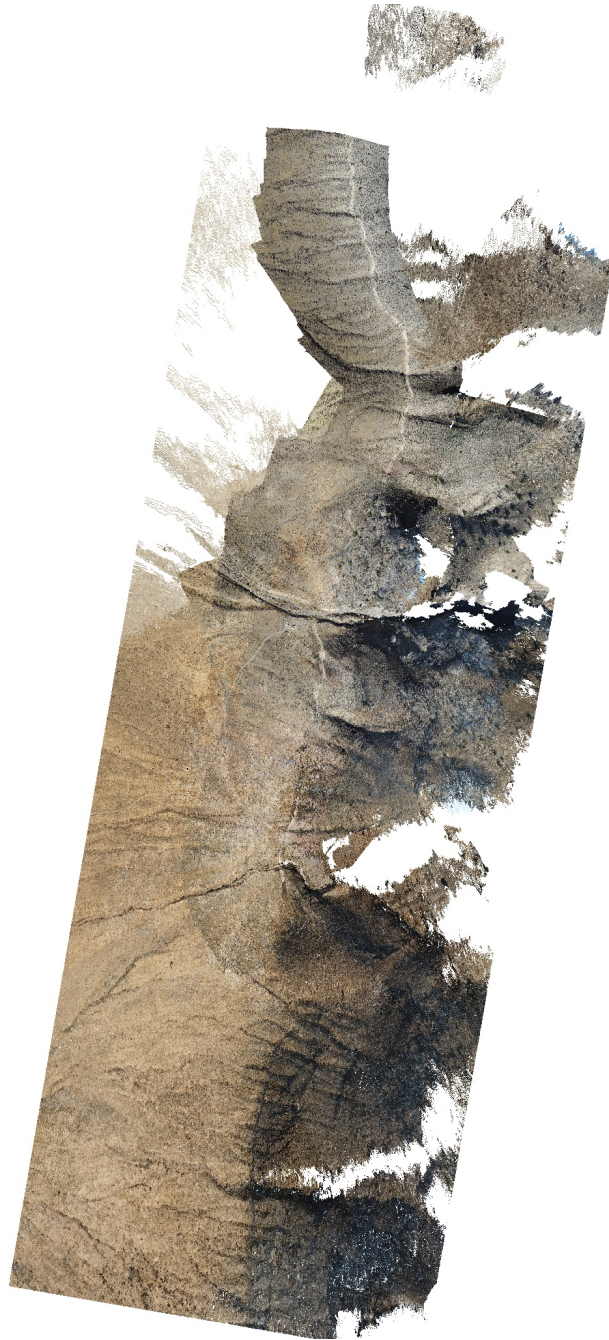


# Agisoft PhotoScan

Processing Report  
07 February 2019



# Survey Data

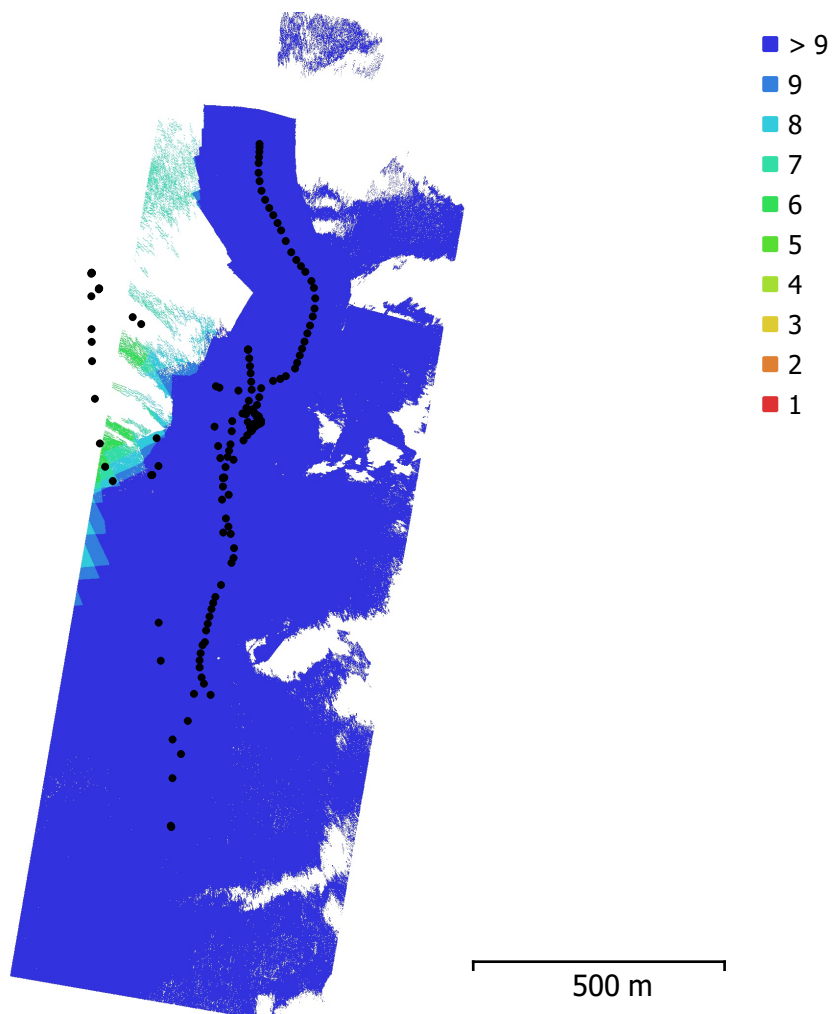


Fig. 1. Camera locations and image overlap.

Number of images:	152	Camera stations:	150
Flying altitude:	271 m	Tie points:	126,246
Ground resolution:	5.66 cm/pix	Projections:	502,440
Coverage area:	0.914 km <sup>2</sup>	Reprojection error:	0.882 pix

Camera Model	Resolution	Focal Length	Pixel Size	Precalibrated
FC220 (4.7mm)	4000 x 3000	4.7 mm	1.56 x 1.56 $\mu$ m	No

Table 1. Cameras.

# Camera Calibration

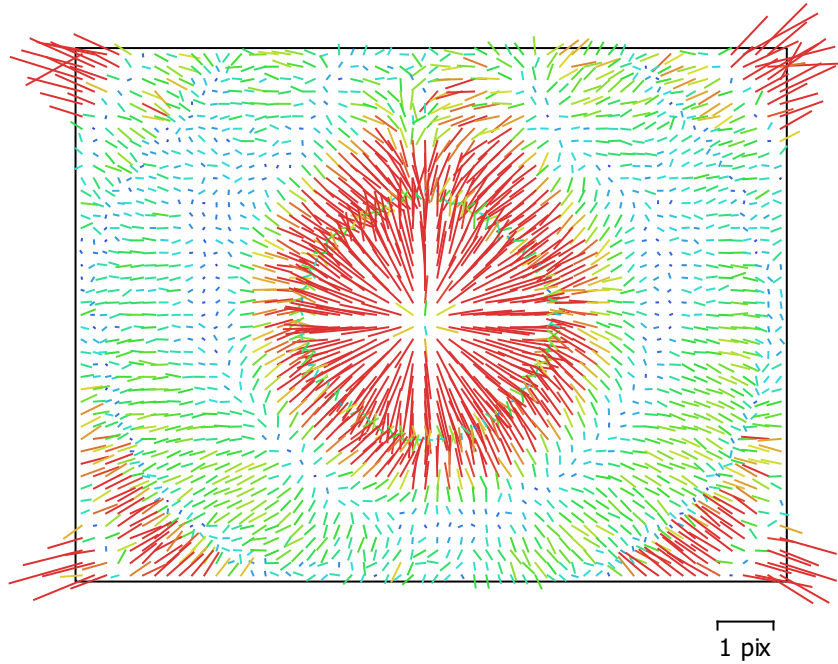


Fig. 2. Image residuals for FC220 (4.7mm).

## FC220 (4.7mm)

152 images

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>4000 x 3000</b>	<b>4.7 mm</b>	<b>1.56 x 1.56 <math>\mu\text{m}</math></b>

	Value	Error	F	Cx	Cy	K1	K2	K3	P1	P2
<b>F</b>	<b>3069.37</b>	0.19	1.00	-0.03	-0.09	0.22	-0.01	0.04	-0.01	-0.01
<b>Cx</b>	<b>-59.6218</b>	0.2		1.00	0.05	0.07	-0.07	0.09	0.92	0.08
<b>Cy</b>	<b>15.9161</b>	0.19			1.00	-0.05	-0.00	0.00	0.05	0.84
<b>K1</b>	<b>0.0379062</b>	0.00012				1.00	-0.93	0.89	0.06	-0.05
<b>K2</b>	<b>-0.110841</b>	0.00041					1.00	-0.98	-0.06	-0.01
<b>K3</b>	<b>0.105343</b>	0.00044						1.00	0.07	0.01
<b>P1</b>	<b>-0.00341178</b>	2.1e-05							1.00	0.03
<b>P2</b>	<b>-0.001068</b>	2e-05								1.00

Table 2. Calibration coefficients and correlation matrix.

# Camera Locations

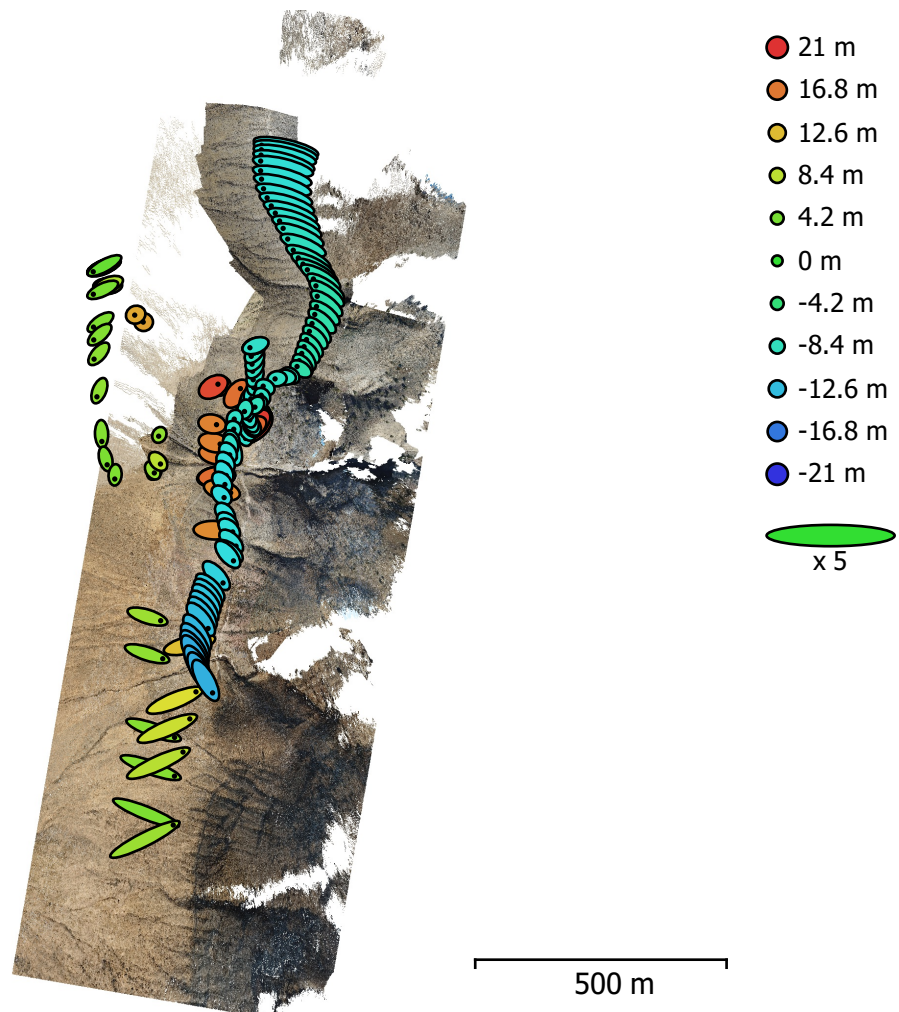


Fig. 3. Camera locations and error estimates.

Z error is represented by ellipse color. X,Y errors are represented by ellipse shape.

Estimated camera locations are marked with a black dot.

X error (m)	Y error (m)	Z error (m)	XY error (m)	Total error (m)
8.03411	4.45855	11.9181	9.18834	15.0488

Table 3. Average camera location error.

X - Longitude, Y - Latitude, Z - Altitude.

# Camera Orientations

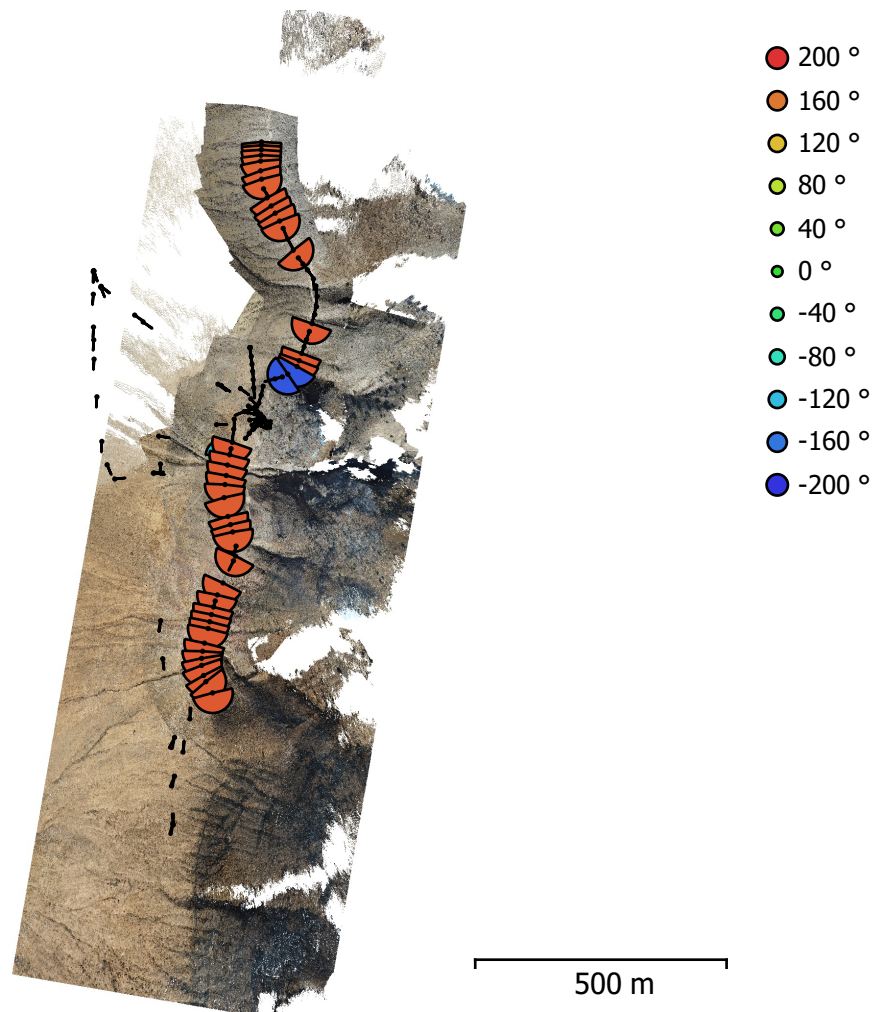


Fig. 4. Camera orientations and error estimates.  
Arcs represent yaw error estimates.

Yaw error (°)	Pitch error (°)	Roll error (°)	Total error (°)
91.4901	1.57827	9.45369	91.9908

Table 4. Average camera rotation error.



# Digital Elevation Model

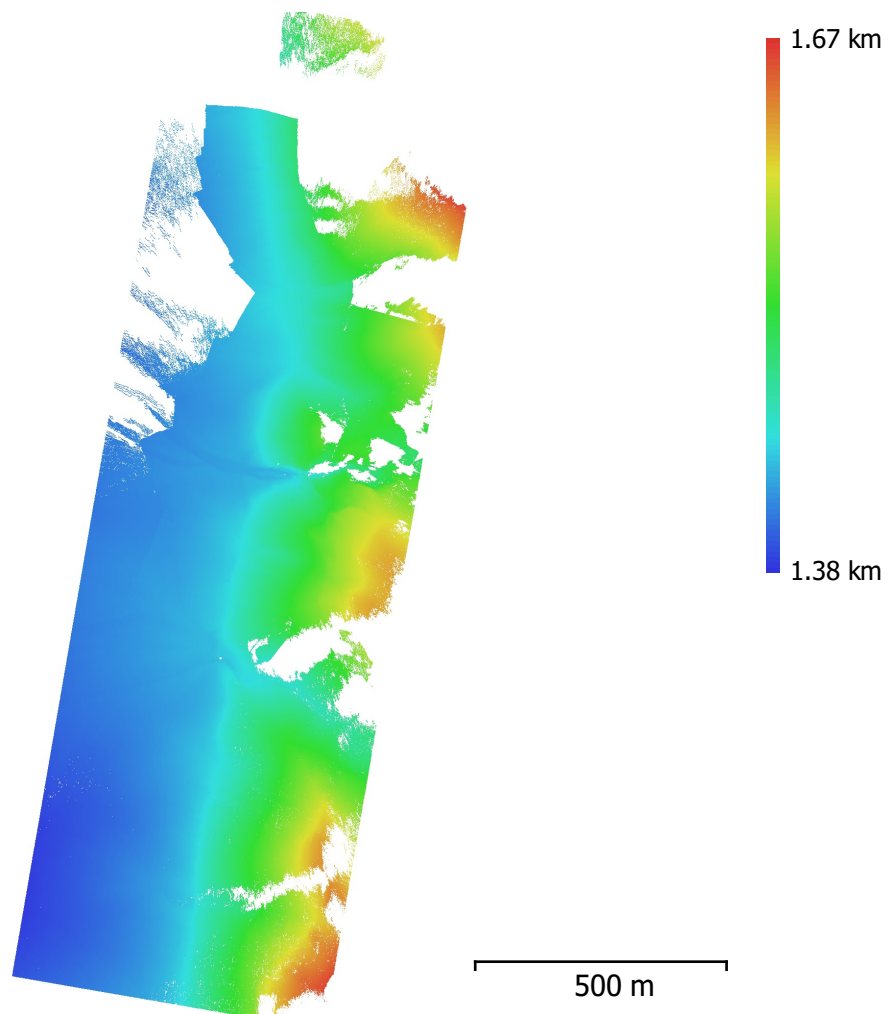


Fig. 5. Reconstructed digital elevation model.

Resolution: unknown

Point density: unknown

# Processing Parameters

## General

Cameras	152
Aligned cameras	150
Coordinate system	WGS 84 (EPSG::4326)
Rotation angles	Yaw, Pitch, Roll

## Point Cloud

Points	126,246 of 139,898
RMS reprojection error	0.317727 (0.882045 pix)
Max reprojection error	0.968833 (28.2973 pix)
Mean key point size	2.89376 pix
Point colors	3 bands, uint8
Key points	No
Average tie point multiplicity	4.21955

## Alignment parameters

Accuracy	High
Generic preselection	No
Reference preselection	Yes
Key point limit	40,000
Tie point limit	4,000
Adaptive camera model fitting	No
Matching time	8 minutes 42 seconds
Alignment time	2 minutes 3 seconds

## Depth Maps

Count	150
<b>Reconstruction parameters</b>	
Quality	High
Filtering mode	Aggressive
Processing time	11 minutes 7 seconds

## Dense Point Cloud

Points	47,986,206
Point colors	3 bands, uint8
<b>Reconstruction parameters</b>	
Quality	High
Depth filtering	Aggressive
Depth maps generation time	11 minutes 7 seconds
Dense cloud generation time	16 days 20 hours

## Software

Version	1.4.4 build 6848
Platform	Windows 64