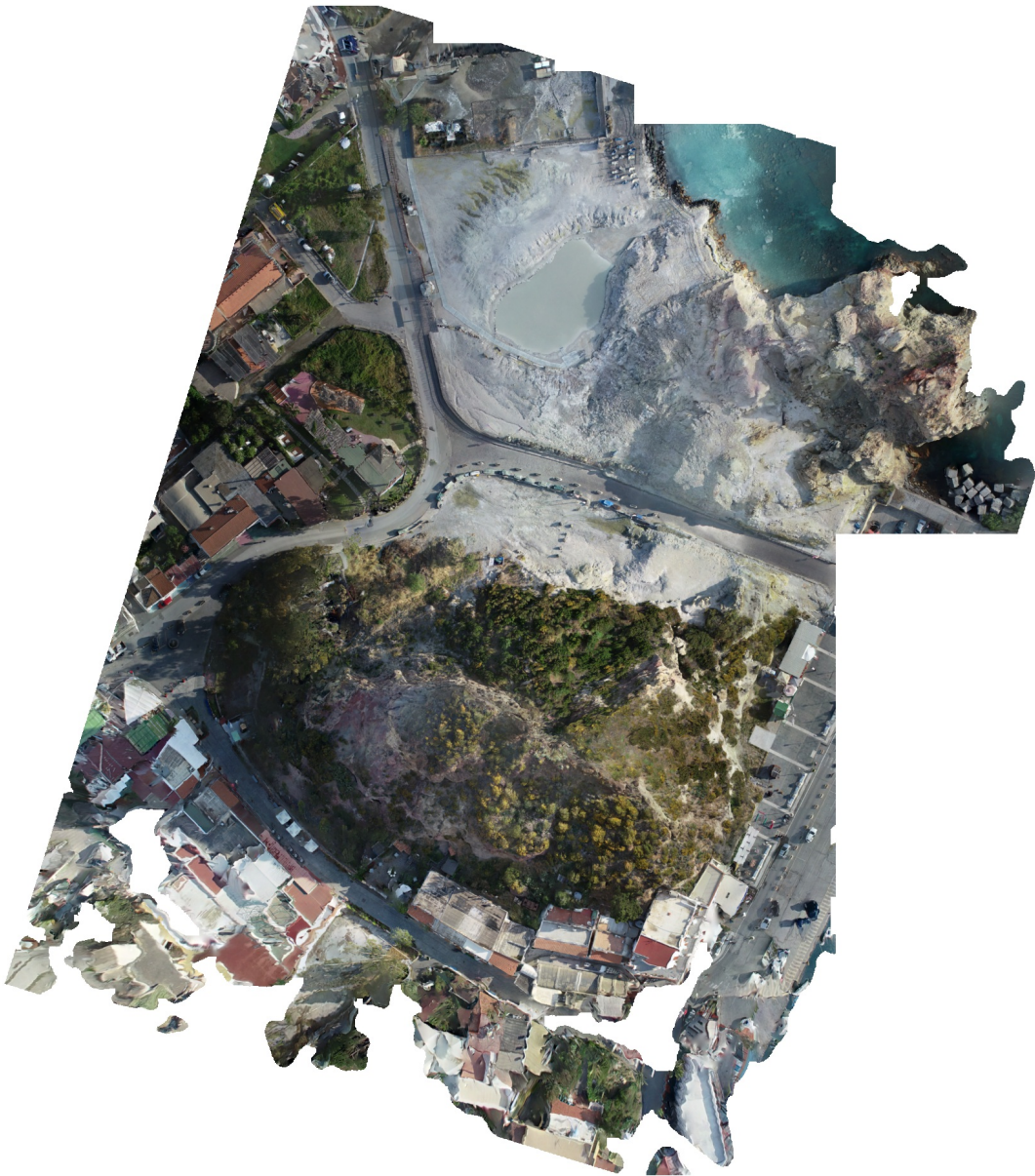


# Agisoft PhotoScan

Processing Report  
29 October 2018



# Survey Data

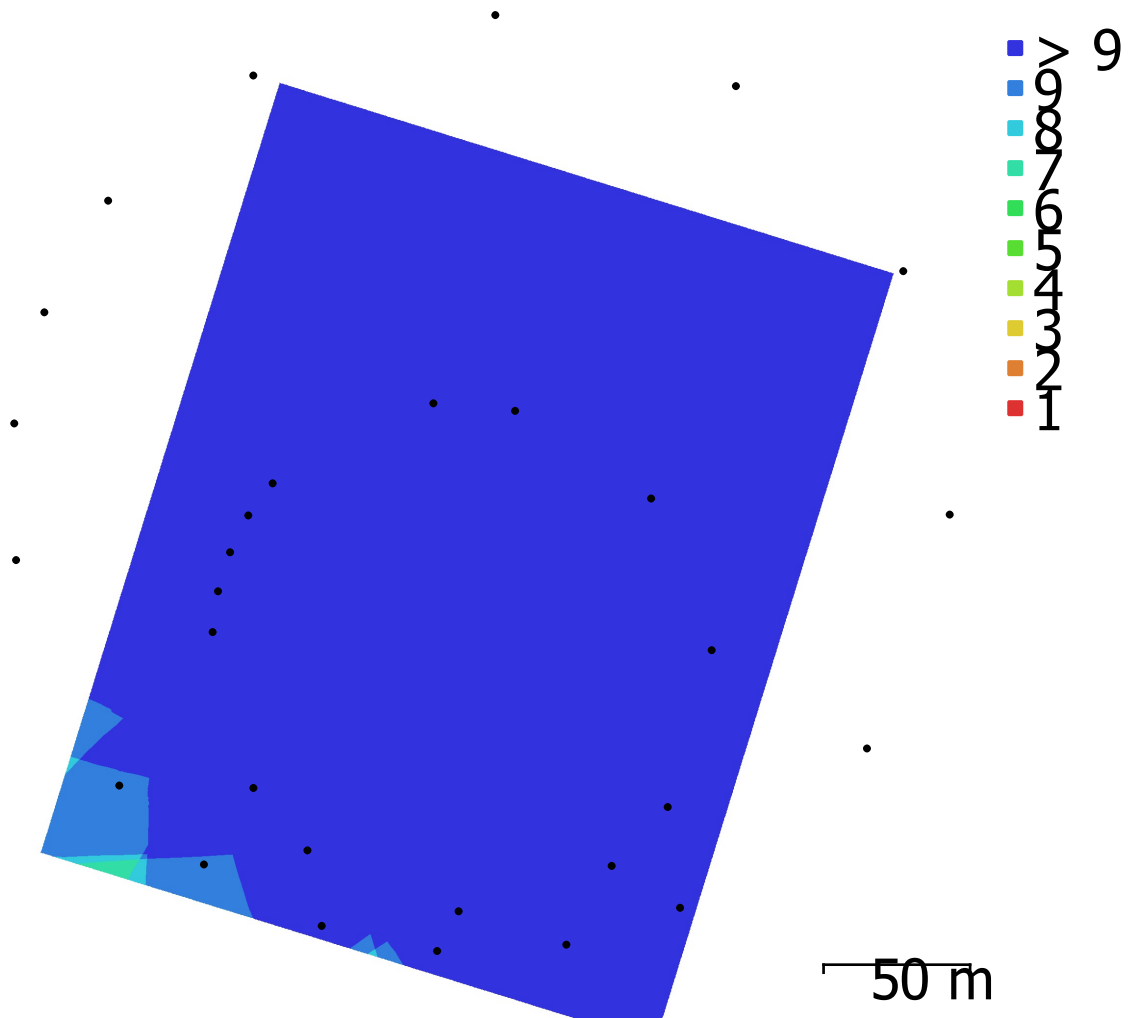


Fig. 1. Camera locations and image overlap.

Number of images:	30	Camera stations:	30
Flying altitude:	127 m	Tie points:	25,213
Ground resolution:	2.86 cm/pix	Projections:	57,905
Coverage area:	0.0601 km <sup>2</sup>	Reprojection error:	0.707 pix

Camera Model	Resolution	Focal Length	Pixel Size	Precalibrated
FC6310 (8.8mm)	5472 x 3648	8.8 mm	2.41 x 2.41 μm	No

Table 1. Cameras.

# Camera Calibration

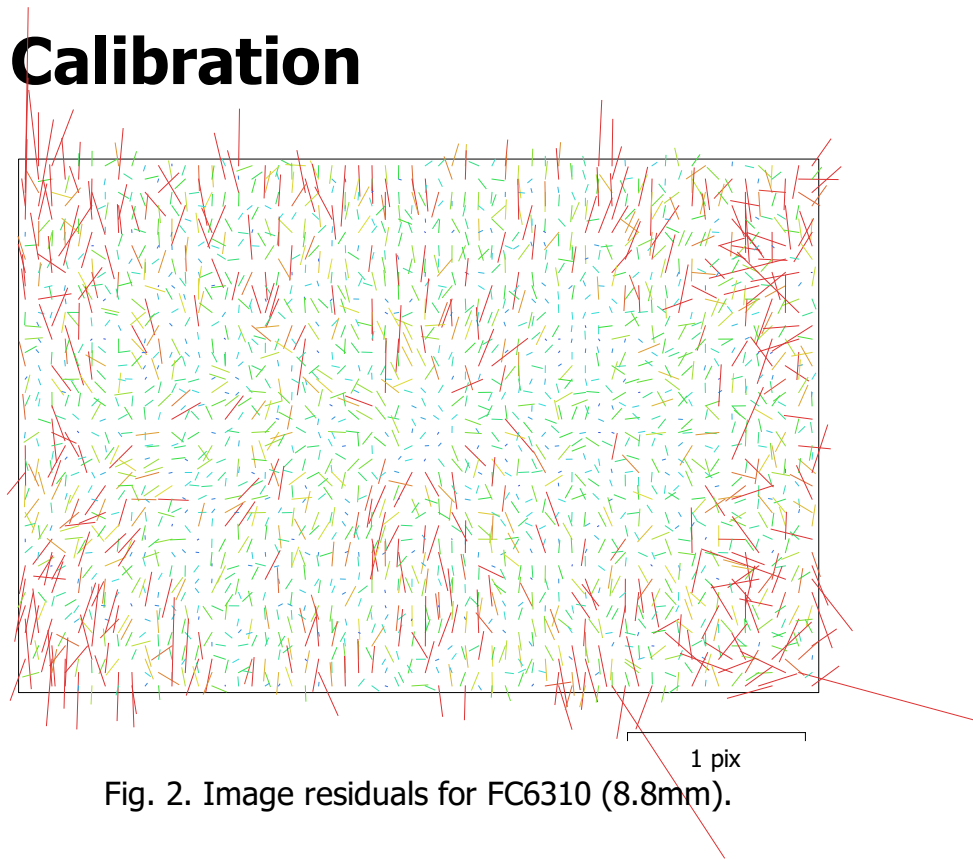


Fig. 2. Image residuals for FC6310 (8.8mm).

## FC6310 (8.8mm)

30 images

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>5472 x 3648</b>	<b>8.8 mm</b>	<b>2.41 x 2.41 <math>\mu</math>m</b>

	Value	Error	F	Cx	Cy	K1	K2	K3	P1	P2
<b>F</b>	<b>3663.1</b>	0.28	1.00	0.05	-0.83	-0.17	0.16	-0.13	0.12	-0.45
<b>Cx</b>	<b>-13.8515</b>	0.27		1.00	-0.00	0.05	-0.05	0.05	0.92	0.01
<b>Cy</b>	<b>5.51611</b>	0.37			1.00	-0.10	0.08	-0.08	-0.06	0.60
<b>K1</b>	<b>0.00201908</b>	0.00018				1.00	-0.95	0.88	0.05	-0.19
<b>K2</b>	<b>-0.0113573</b>	0.00053					1.00	-0.98	-0.05	0.13
<b>K3</b>	<b>0.0123404</b>	0.00048						1.00	0.04	-0.09
<b>P1</b>	<b>-2.15389e-05</b>	2.6e-05							1.00	-0.05
<b>P2</b>	<b>-0.000133249</b>	1.7e-05								1.00

Table 2. Calibration coefficients and correlation matrix.

# Camera Locations

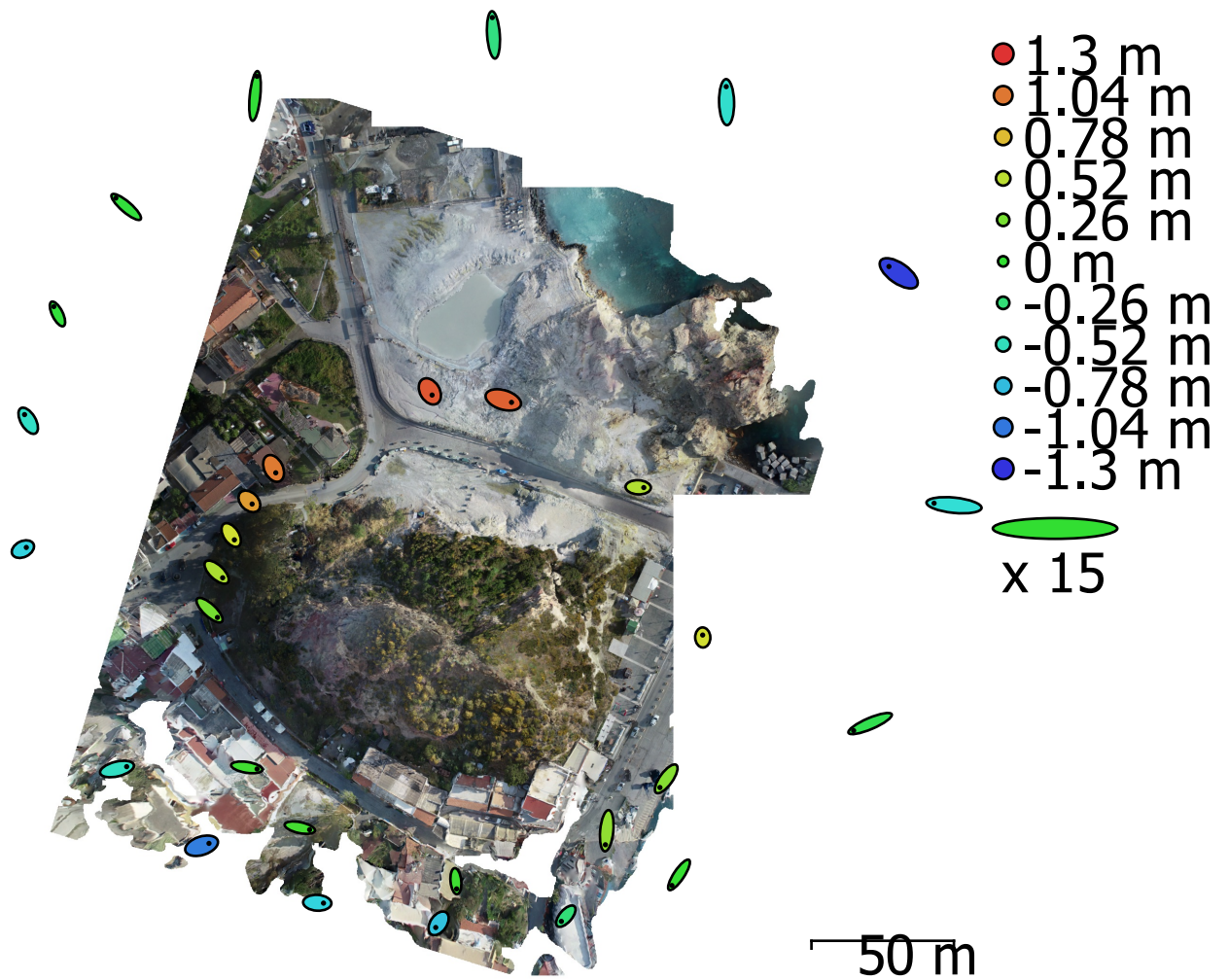


Fig. 3. Camera locations and error estimates.

Z error is represented by ellipse color. X,Y errors are represented by ellipse shape.

Estimated camera locations are marked with a black dot.

X error (cm)	Y error (cm)	Z error (cm)	XY error (cm)	Total error (cm)
34.6857	36.902	62.0584	50.6444	80.1005

Table 3. Average camera location error.

X - Longitude, Y - Latitude, Z - Altitude.

# Digital Elevation Model

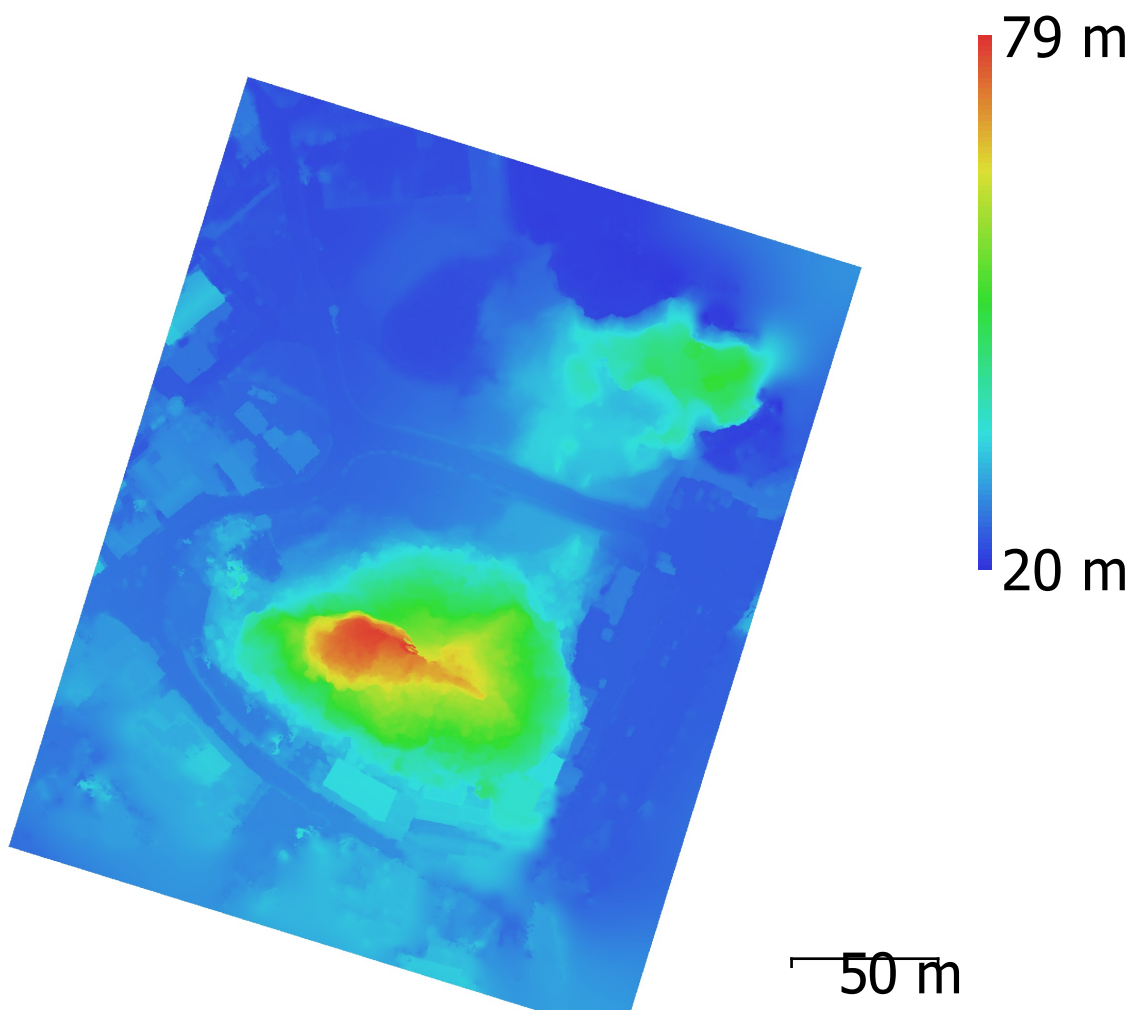


Fig. 4. Reconstructed digital elevation model.

Resolution: 5.72 cm/pix  
Point density: 306 points/m<sup>2</sup>

# Processing Parameters

## General

Cameras	30
Aligned cameras	30
Coordinate system	WGS 84 (EPSG::4326)
Rotation angles	Yaw, Pitch, Roll

## Point Cloud

Points	25,213 of 26,329
RMS reprojection error	0.100293 (0.70713 pix)
Max reprojection error	0.319926 (22.9515 pix)
Mean key point size	5.26048 pix
Point colors	3 bands, uint8
Key points	No
Average tie point multiplicity	2.32789

## Alignment parameters

Accuracy	High
Generic preselection	Yes
Reference preselection	Yes
Key point limit	40,000
Tie point limit	4,000
Adaptive camera model fitting	No
Matching time	3 minutes 29 seconds
Alignment time	11 seconds

## Optimization parameters

Parameters	f, cx, cy, k1-k3, p1, p2
Adaptive camera model fitting	No
Optimization time	0 seconds

## Dense Point Cloud

Points	17,314,350
Point colors	3 bands, uint8

## Reconstruction parameters

Quality	High
Depth filtering	Aggressive
Depth maps generation time	21 minutes 55 seconds
Dense cloud generation time	7 minutes 47 seconds

## Model

Faces	3,462,838
Vertices	1,736,468
Vertex colors	3 bands, uint8
Texture	4,096 x 4,096 x 2, 4 bands, uint8

## Reconstruction parameters

Surface type	Arbitrary
Source data	Dense
Interpolation	Enabled
Quality	High
Depth filtering	Aggressive
Face count	3,462,839
Processing time	20 minutes 20 seconds

## Texturing parameters

Mapping mode	Generic
Blending mode	Mosaic
Texture size	4,096 x 4,096
Enable hole filling	Yes
Enable ghosting filter	Yes
UV mapping time	1 minutes 12 seconds
Blending time	8 minutes 29 seconds

**DEM**

Size 5,085 x 5,725  
Coordinate system WGS 84 (EPSG::4326)

**Reconstruction parameters**

Source data Dense cloud  
Interpolation Enabled  
Processing time 22 seconds

**Orthomosaic**

Size 9,485 x 11,159  
Coordinate system WGS 84 (EPSG::4326)  
Colors 3 bands, uint8

**Reconstruction parameters**

Blending mode Mosaic  
Surface Mesh  
Enable hole filling Yes  
Processing time 7 minutes 1 seconds

**Software**

Version 1.4.3 build 6529  
Platform Windows 64